

HEAP DATA STRUCTURE

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Heap

Heap is a specialized binary tree-based data structure that satisfies the following conditions:

1. A heap is an almost complete binary tree: the first element is stored in the root.

Then the next level is filled from the left to the right.

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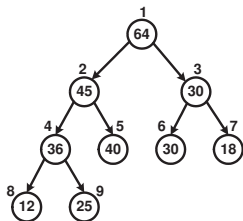
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It is easy to show that **the highest priority** element is always stored at the root.

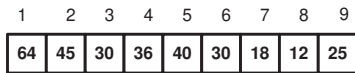
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An example of a heap is given in the following figure:



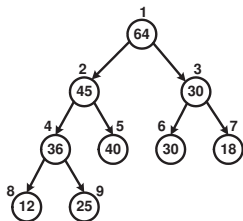
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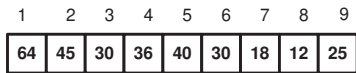
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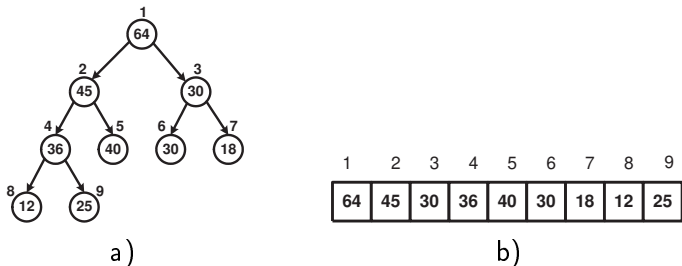


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Given a node a_i at index i , its children are at indices $2i$ and $2i + 1$ (elements a_{2i} and a_{2i+1}).

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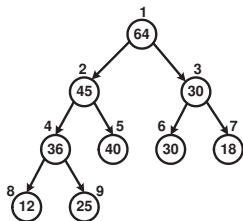


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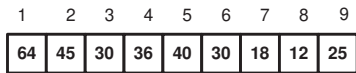
A parent of vertex a_i is at index $j = \lfloor i/2 \rfloor$ (element a_j).

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A parent of vertex a_i is at index $j = \lfloor i/2 \rfloor$ (element a_j).

This simple indexing scheme makes it efficient to move "up" or "down" the binary tree.

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All leaves of the binary tree are already ordered. Such elements are at indices $(\frac{N}{2} + 1), \dots, N$.

Then we take elements $\frac{N}{2}, \frac{N}{2} - 1, \dots, 1$ and apply **recursive** checking of the ordering condition.

If this condition is not satisfied **sift-down** transformation is used to restore heap condition, i.e. the given element is swapped with its largest child.

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This checking step is continued in a new place till heap condition is satisfied (recursion technique).

Heap algorithm

MakeHeap ()

begin

(1) **for** ($i=1; i \leq N; i++$) **do**

(2) $a_i = e_i;$

end do

(3) **for** ($i=N/2; i > 0; i--$) **do**

(4) HeapDownOrder (i, N);

end do

end MakeHeap

This function is iterative, since at each step only one sub-tree is considered.

```
HeapDownOrder ( p, N )  
begin  
  (1) i=p;   j = 2i;  
  (2) while ( j ≤ N ) do  
  (3)     k = j;  
  (4)     if ( (j+1) ≤ N ) then  
  (5)       if (  $a_{j+1} > a_j$  ) k = j+1;  
  (6)     if (  $a_i < a_k$  ) then  
  (7)       swap (  $a_i, a_k$  );  
  (8)       i = k;   j= 2i;  
  (9)     else  
  (10)      j = N+1;  
end HeapDownOrder
```

Make a heap from array

$A = (10, 37, 18, 13, 22, 14, 25, 10, 12, 28)$.

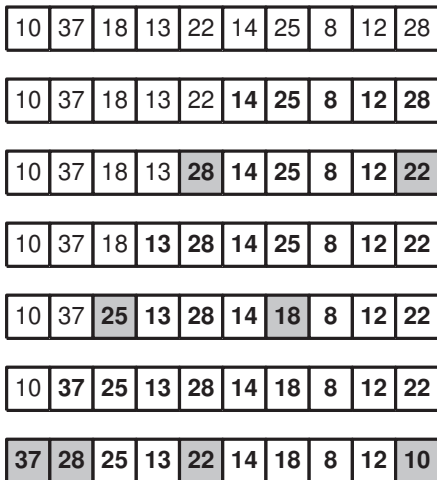


FIGURE: Construction of heap.

Now we estimate the complexity of this algorithm.

Since a heap is balanced binary tree, its height is equal to $\log N$.

For each activation of `HeapDownOrder` algorithm the number of comparisons is not larger than $2 \log N$ and the number of swappings is not larger than $\log N$.

Thus total costs can be bounded from above as

$$L(N) \leq N \log N, \quad S(N) \leq \frac{1}{2} N \log N.$$